

Near-Term Servicing Plans: A Canadian Perspective

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Outline

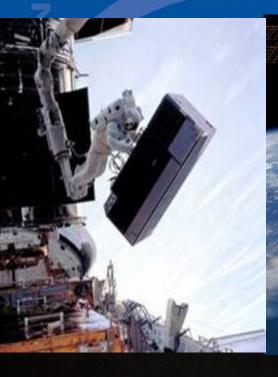
- Canadian Heritage
- Current Activities
- Future Opportunities
 - ◆ LEO
 - Exploration
- Conclusion
- Questions for Panel



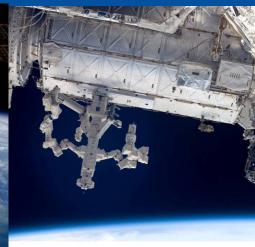
Canadian Space

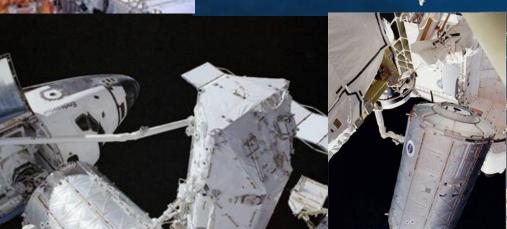
Agence spatiale 30 Years of Robotic Operations (Canadienne 30 Years on Shuttle / Station













CSA ASC

NASA Shuttle Canadarm (1981 - 2011)



Servicing of Hubble Space Telescope







Canada

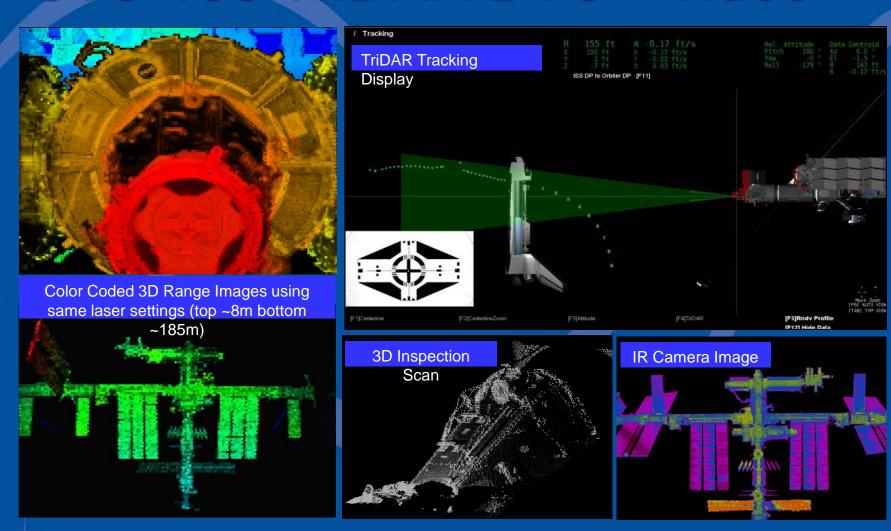
Participation in International On-Orbit Servicing (OOS) Forums

- International Workshop on OOS, Cologne, Germany, 2002
 - http://www.on-orbit-servicing.com/workshop_2002/index02.html
 - http://www.on-orbit-servicing.com/workshop_2002/OOS-Docs-ST6-1/2-2.pdf
- International Workshop on OOS, Vancouver, Canada, 2004
 - http://www.on-orbit-servicing.com/workshop_2004/index04.html
 - http://www.on-orbitservicing.com/pdf/OOS2004_presentations_pdf/SettingTheScene_Piedboeuf.pdf
- International Workshop on OOS, GSFC, Greenbelt, MD, 2010
 - http://ssco.gsfc.nasa.gov/workshop_2010.html
 - http://ssco.gsfc.nasa.gov/workshop_2010/day2/Daniel_Rey/GSFC_RFI_CSA_Pr esentation_RevA_May2010.pdf





STS-135 TriDAR DTO - Video



On-Going Servicing Activities on ISS

Using Dextre to perform an RPCM replacement

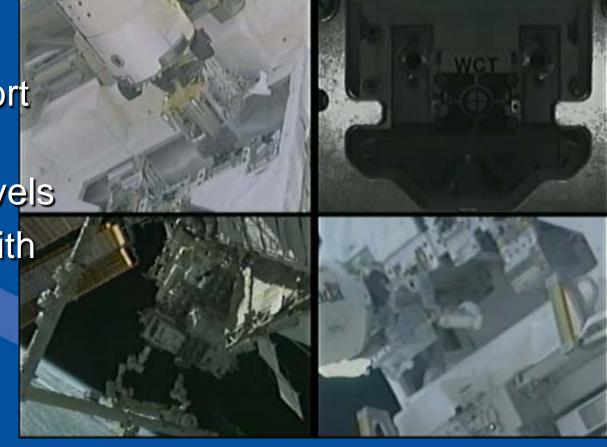






On-Going Servicing Activities on ISS

- Robotic Refuelling Mission
- MSS arms and end-effectors
- CSA Ops support
- Achieved new performance levels
- Collaboration with GSFC
 - Tools
 - Task boards





Next Generation Canadarm

- Funded by Canada's Economic Action Plan, from Budget 2009.
 - Project completion: March 31, 2012
- Prime contractor: MDA, Brampton
- Project objectives:
 - Develop terrestrial prototypes of next generation of Canadarm for on-orbit servicing
 - Deliver four testbeds and two control stations:
 - Next Generation Small Canadarm (NGSC)
 - Next Generation Large Canadarm (NGLC)
 - Proximity Operations Station (POST)
 - Semi-Autonomous Docking System (SADS)
 - Mission Operations Station (2x) (MOS)
 - Demonstrate functionalities that are pertinent to on-orbit robotic servicing





Next Generation Canadarm





NGC - Video





MSS Evolution

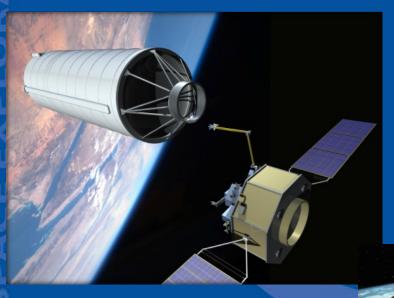
- Advanced Dextre Tools DTOs
 - Reduce EVA time, maximize robotic servicing capabilities
 - Demonstrate NGC tool technologies
 - Inspection and camera tools
- Advance Canadarm 2 capabilities
 - New camera systems
 - Visual servoing
 - Auto-capture of fixed object, e.g. ORU
 - Auto-capture of free-flyers, e.g. cargo vehicles, satellites
 - Semi-Autonomous operations, minimize crew time
- DTOs to support future exploration endeavours
 - Optical Testbed and Integration on ISS experiment (OPTIIX)
 - Telescopic boom featuring a high packing ratio making it compatible with size of future exploration vehicles
 - Autonomous inspection & servicing

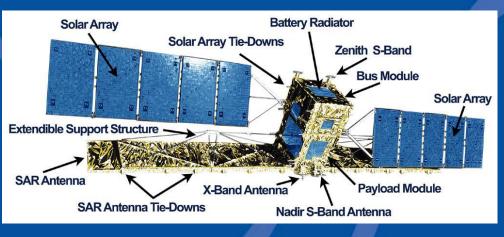




OOS Future Opportunities







Legacy Government Satellites, e.g. Radarsat 1

Orbital Debris Removal



Failed Satellites, e.g. Envisat





OOS Future Opportunities

Exploration

Fuel Depot



EML Spacecraft

Next Gen. Astronomy Satellite





Conclusions

- OOS has been considered for many years
- Technologies enabling OOS are mature
- OOS has been achieved through collaboration
- Many OOS opportunities require International participation/agreements
- CSA is open for collaboration





Questions for Panel

- Why OOS now?
- What are the key enablers for a commercial success?
- What can governments, agencies do to enable OOS?

